
python-zeroconf

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GitHub (code repository, issues): <https://github.com/jstasiak/python-zeroconf>

PyPI (installable, stable distributions): <https://pypi.org/project/zeroconf>. You can install python-zeroconf using pip:

```
pip install zeroconf
```

python-zeroconf works with CPython 3.6+ and PyPy 3 implementing Python 3.6+.

1.1 python-zeroconf API reference

Multicast DNS Service Discovery for Python, v0.14-wmcbrine Copyright 2003 Paul Scott-Murphy, 2014 William McBrine

This module provides a framework for the use of DNS Service Discovery using IP multicast.

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```
class zeroconf.Zeroconf (interfaces: Union[List[Union[str, int, Tuple[Tuple[str, int, int], int]]], zero-
                        conf._utils.net.InterfaceChoice] = <InterfaceChoice.All: 2>, unicast: bool
                        = False, ip_version: Optional[zeroconf._utils.net.IPVersion] = None, ap-
                        ple_p2p: bool = False)
```

Bases: zeroconf._logger.QuietLogger

Implementation of Zeroconf Multicast DNS Service Discovery

Supports registration, unregistration, queries and browsing.

```
add_listener (listener: zeroconf._updates.RecordUpdateListener, question:
                Union[zeroconf._dns.DNSQuestion, List[zeroconf._dns.DNSQuestion], None])
                → None
```

Adds a listener for a given question. The listener will have its update_record method called when information is available to answer the question(s).

This function is threadsafe

add_service_listener (*type_*: str, *listener*: zeroconf._services.ServiceListener) → None

Adds a listener for a particular service type. This object will then have its `add_service` and `remove_service` methods called when services of that type become available and unavailable.

async_add_listener (*listener*: zeroconf._updates.RecordUpdateListener, *question*: Union[zeroconf._dns.DNSQuestion, List[zeroconf._dns.DNSQuestion], None]) → None

Adds a listener for a given question. The listener will have its `update_record` method called when information is available to answer the question(s).

This function is not threadsafe and must be called in the eventloop.

async_check_service (*info*: zeroconf._services.info.ServiceInfo, *allow_name_change*: bool, *cooperating_responders*: bool = False) → None

Checks the network for a unique service name, modifying the ServiceInfo passed in if it is not unique.

async_notify_all () → None

Schedule an `async_notify_all`.

async_register_service (*info*: zeroconf._services.info.ServiceInfo, *ttl*: Optional[int] = None, *allow_name_change*: bool = False, *cooperating_responders*: bool = False) → Awaitable[T_co]

Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service. The name of the service may be changed if needed to make it unique on the network. Additionally multiple cooperating responders can register the same service on the network for resilience (if you want this behavior set `cooperating_responders` to `True`).

async_remove_listener (*listener*: zeroconf._updates.RecordUpdateListener) → None

Removes a listener.

This function is not threadsafe and must be called in the eventloop.

async_send (*out*: zeroconf._protocol.outgoing.DNSOutgoing, *addr*: Optional[str] = None, *port*: int = 5353, *v6_flow_scope*: Union[Tuple[()], Tuple[int, int]] = (), *transport*: Optional[asyncio.transports.DatagramTransport] = None) → None

Sends an outgoing packet.

async_unregister_all_services () → None

Unregister all registered services.

Unlike `async_register_service` and `async_unregister_service`, this method does not return a future and is always expected to be awaited since its only called at shutdown.

async_unregister_service (*info*: zeroconf._services.info.ServiceInfo) → Awaitable[T_co]

Unregister a service.

async_update_service (*info*: zeroconf._services.info.ServiceInfo) → Awaitable[T_co]

Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service.

async_wait (*timeout*: float) → None

Calling task waits for a given number of milliseconds or until notified.

async_wait_for_start () → None

Wait for start up for actions that require a running Zeroconf instance.

Throws `NotRunningException` if the instance is not running or could not be started.

close () → None

Ends the background threads, and prevent this instance from servicing further queries.

This method is idempotent and irreversible.

generate_service_broadcast (*info*: *zeroconf._services.info.ServiceInfo*, *ttl*: *Optional[int]*, *broadcast_addresses*: *bool = True*) → *zeroconf._protocol.outgoing.DNSOutgoing*
 Generate a broadcast to announce a service.

generate_service_query (*info*: *zeroconf._services.info.ServiceInfo*) → *zeroconf._protocol.outgoing.DNSOutgoing*
 Generate a query to lookup a service.

generate_unregister_all_services () → *Optional[zeroconf._protocol.outgoing.DNSOutgoing]*
 Generate a *DNSOutgoing* goodbye for all services and remove them from the registry.

get_service_info (*type_*: *str*, *name*: *str*, *timeout*: *int = 3000*, *question_type*: *Optional[zeroconf._dns.DNSQuestionType] = None*) → *Optional[zeroconf._services.info.ServiceInfo]*
 Returns network's service information for a particular name and type, or *None* if no service matches by the timeout, which defaults to 3 seconds.

handle_assembled_query (*packets*: *List[zeroconf._protocol.incoming.DNSIncoming]*, *addr*: *str*, *port*: *int*, *transport*: *asyncio.transports.DatagramTransport*, *v6_flow_scope*: *Union[Tuple[()], Tuple[int, int]] = ()*) → *None*
 Respond to a (re)assembled query.

 If the protocol recieved packets with the TC bit set, it will wait a bit for the rest of the packets and only call *handle_assembled_query* once it has a complete set of packets or the timer expires. If the TC bit is not set, a single packet will be in packets.

handle_response (*msg*: *zeroconf._protocol.incoming.DNSIncoming*) → *None*
 Deal with incoming response packets. All answers are held in the cache, and listeners are notified.

notify_all () → *None*
 Notifies all waiting threads and notify listeners.

register_service (*info*: *zeroconf._services.info.ServiceInfo*, *ttl*: *Optional[int] = None*, *allow_name_change*: *bool = False*, *cooperating_responders*: *bool = False*) → *None*
 Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service. The name of the service may be changed if needed to make it unique on the network. Additionally multiple cooperating responders can register the same service on the network for resilience (if you want this behavior set *cooperating_responders* to *True*).

 While it is not expected during normal operation, this function may raise *EventLoopBlocked* if the underlying call to *register_service* cannot be completed.

remove_all_service_listeners () → *None*
 Removes a listener from the set that is currently listening.

remove_listener (*listener*: *zeroconf._updates.RecordUpdateListener*) → *None*
 Removes a listener.

 This function is threadsafe

remove_service_listener (*listener*: *zeroconf._services.ServiceListener*) → *None*
 Removes a listener from the set that is currently listening.

send (*out*: *zeroconf._protocol.outgoing.DNSOutgoing*, *addr*: *Optional[str] = None*, *port*: *int = 5353*, *v6_flow_scope*: *Union[Tuple[()], Tuple[int, int]] = ()*, *transport*: *Optional[asyncio.transports.DatagramTransport] = None*) → *None*
 Sends an outgoing packet threadsafe.

start () → *None*
 Start Zeroconf.

started

Check if the instance has started.

unregister_all_services () → None

Unregister all registered services.

While it is not expected during normal operation, this function may raise `EventLoopBlocked` if the underlying call to `async_unregister_all_services` cannot be completed.

unregister_service (info: `zeroconf._services.info.ServiceInfo`) → None

Unregister a service.

While it is not expected during normal operation, this function may raise `EventLoopBlocked` if the underlying call to `async_unregister_service` cannot be completed.

update_service (info: `zeroconf._services.info.ServiceInfo`) → None

Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service.

While it is not expected during normal operation, this function may raise `EventLoopBlocked` if the underlying call to `async_update_service` cannot be completed.

```
class zeroconf.ServiceInfo (type_: str, name: str, port: Optional[int] = None, weight: int =
                             0, priority: int = 0, properties: Union[bytes, Dict[KT, VT]] = b'',
                             server: Optional[str] = None, host_ttl: int = 120, other_ttl: int =
                             4500, *, addresses: Optional[List[bytes]] = None, parsed_addresses:
                             Optional[List[str]] = None, interface_index: Optional[int] = None)
```

Bases: `zeroconf._updates.RecordUpdateListener`

Service information.

Constructor parameters are as follows:

- *type_*: fully qualified service type name
- *name*: fully qualified service name
- *port*: port that the service runs on
- *weight*: weight of the service
- *priority*: priority of the service
- *properties*: dictionary of properties (or a bytes object holding the contents of the *text* field). converted to str and then encoded to bytes using UTF-8. Keys with *None* values are converted to value-less attributes.
- *server*: fully qualified name for service host (defaults to name)
- *host_ttl*: ttl used for A/SRV records
- *other_ttl*: ttl used for PTR/TXT records
- *addresses* and *parsed_addresses*: List of IP addresses (either as bytes, network byte order, or in parsed form as text; at most one of those parameters can be provided)
- *interface_index*: scope_id or zone_id for IPv6 link-local addresses i.e. an identifier of the interface where the peer is connected to

addresses

IPv4 addresses of this service.

Only IPv4 addresses are returned for backward compatibility. Use `addresses_by_version()` or `parsed_addresses()` to include IPv6 addresses as well.

addresses_by_version (version: `zeroconf._utils.net.IPVersion`) → List[bytes]

List addresses matching IP version.

async_request (zc: *Zeroconf*, timeout: *float*, question_type: *Optional[zeroconf._dns.DNSQuestionType] = None*) → bool
 Returns true if the service could be discovered on the network, and updates this object with details discovered.

async_update_records (zc: *Zeroconf*, now: *float*, records: *List[zeroconf._updates.RecordUpdate]*) → None
 Updates service information from a DNS record.
 This method will be run in the event loop.

dns_addresses (override_ttl: *Optional[int] = None*, version: *zeroconf._utils.net.IPVersion = <IPVersion.All: 3>*, created: *Optional[float] = None*) → *List[zeroconf._dns.DNSAddress]*
 Return matching DNSAddress from ServiceInfo.

dns_pointer (override_ttl: *Optional[int] = None*, created: *Optional[float] = None*) → *zeroconf._dns.DNSPointer*
 Return DNSPointer from ServiceInfo.

dns_service (override_ttl: *Optional[int] = None*, created: *Optional[float] = None*) → *zeroconf._dns.DNSService*
 Return DNSService from ServiceInfo.

dns_text (override_ttl: *Optional[int] = None*, created: *Optional[float] = None*) → *zeroconf._dns.DNSText*
 Return DNSText from ServiceInfo.

generate_request_query (zc: *Zeroconf*, now: *float*, question_type: *Optional[zeroconf._dns.DNSQuestionType] = None*) → *zeroconf._protocol.outgoing.DNSOutgoing*
 Generate the request query.

get_name () → str
 Name accessor

load_from_cache (zc: *Zeroconf*) → bool
 Populate the service info from the cache.
 This method is designed to be threadsafe.

name
 The name of the service.

parsed_addresses (version: *zeroconf._utils.net.IPVersion = <IPVersion.All: 3>*) → *List[str]*
 List addresses in their parsed string form.

parsed_scoped_addresses (version: *zeroconf._utils.net.IPVersion = <IPVersion.All: 3>*) → *List[str]*
 Equivalent to parsed_addresses, with the exception that IPv6 Link-Local addresses are qualified with %<interface_index> when available

properties
 If properties were set in the constructor this property returns the original dictionary of type *Dict[Union[bytes, str], Any]*.
 If properties are coming from the network, after decoding a TXT record, the keys are always bytes and the values are either bytes, if there was a value, even empty, or *None*, if there was none. No further decoding is attempted. The type returned is *Dict[bytes, Optional[bytes]]*.

request (zc: *Zeroconf*, timeout: *float*, question_type: *Optional[zeroconf._dns.DNSQuestionType] = None*) → bool
 Returns true if the service could be discovered on the network, and updates this object with details discovered.

While it is not expected during normal operation, this function may raise `EventLoopBlocked` if the underlying call to `async_request` cannot be completed.

update_record (zc: *Zeroconf*, now: *float*, record: *Optional[zeroconf._dns.DNSRecord]*) → *None*

Updates service information from a DNS record.

This method is deprecated and will be removed in a future version. `update_records` should be implemented instead.

This method will be run in the event loop.

```
class zeroconf.ServiceBrowser (zc: Zeroconf, type_: Union[str, list], handlers: Union[zeroconf._services.ServiceListener, List[Callable[[...], None]], None] = None, listener: Optional[zeroconf._services.ServiceListener] = None, addr: Optional[str] = None, port: int = 5353, delay: int = 1000, question_type: Optional[zeroconf._dns.DNSQuestionType] = None)
```

Bases: `zeroconf._services.browse._ServiceBrowserBase`, `threading.Thread`

Used to browse for a service of a specific type.

The listener object will have its `add_service()` and `remove_service()` methods called when this browser discovers changes in the services availability.

cancel () → *None*

Cancel the browser.

run () → *None*

Run the browser thread.

```
class zeroconf.DNSQuestionType
```

Bases: `enum.Enum`

An MDNS question type.

“QU” - questions requesting unicast responses “QM” - questions requesting multicast responses <https://datatracker.ietf.org/doc/html/rfc6762#section-5.4>

QM = 2

QU = 1

```
class zeroconf.InterfaceChoice
```

Bases: `enum.Enum`

An enumeration.

All = 2

Default = 1

```
class zeroconf.ServiceStateChange
```

Bases: `enum.Enum`

An enumeration.

Added = 1

Removed = 2

Updated = 3

```
class zeroconf.IPVersion
```

Bases: `enum.Enum`

An enumeration.

All = 3

V4Only = 1

V6Only = 2

class zeroconf.**ZeroconfServiceTypes**

Bases: zeroconf._services.ServiceListener

Return all of the advertised services on any local networks

add_service (zc: zeroconf._core.Zeroconf, type_: str, name: str) → None
Service added.

classmethod find (zc: Optional[zeroconf._core.Zeroconf] = None, timeout: Union[int, float] = 5, interfaces: Union[List[Union[str, int, Tuple[Tuple[str, int, int], int]]], zeroconf._utils.net.InterfaceChoice] = <InterfaceChoice.All: 2>, ip_version: Optional[zeroconf._utils.net.IPVersion] = None) → Tuple[str, ...]
Return all of the advertised services on any local networks.

Parameters

- **zc** – Zeroconf() instance. Pass in if already have an instance running or if non-default interfaces are needed
- **timeout** – seconds to wait for any responses
- **interfaces** – interfaces to listen on.
- **ip_version** – IP protocol version to use.

Returns tuple of service type strings

remove_service (zc: zeroconf._core.Zeroconf, type_: str, name: str) → None
Service removed.

update_service (zc: zeroconf._core.Zeroconf, type_: str, name: str) → None
Service updated.

class zeroconf.**RecordUpdate** (new, old)

Bases: tuple

new

Alias for field number 0

old

Alias for field number 1

class zeroconf.**RecordUpdateListener**

Bases: object

Base call for all record listeners.

All listeners passed to `async_add_listener` should use `RecordUpdateListener` as a base class. In the future it will be required.

async_update_records (zc: Zeroconf, now: float, records: List[zeroconf._updates.RecordUpdate]) → None
Update multiple records in one shot.

All records that are received in a single packet are passed to `update_records`.

This implementation is a compatibility shim to ensure older code that uses `RecordUpdateListener` as a base class will continue to get calls to `update_record`. This method will raise `NotImplementedError` in a future version.

At this point the cache will not have the new records

Records are passed as a list of `RecordUpdate`. This allows consumers of `async_update_records` to avoid cache lookups.

This method will be run in the event loop.

`async_update_records_complete()` → None

Called when a record update has completed for all handlers.

At this point the cache will have the new records.

This method will be run in the event loop.

`update_record(zc: Zeroconf, now: float, record: zeroconf._dns.DNSRecord)` → None

Update a single record.

This method is deprecated and will be removed in a future version. `update_records` should be implemented instead.

`zeroconf.current_time_millis()` → float

Current time in milliseconds.

The current implementation uses *time.monotonic* but may change in the future.

exception `zeroconf.Error`

Bases: `Exception`

Base class for all zeroconf exceptions.

exception `zeroconf.AbstractMethodException`

Bases: `zeroconf._exceptions.Error`

Exception when a required method is not implemented.

exception `zeroconf.BadTypeInNameException`

Bases: `zeroconf._exceptions.Error`

Exception when the type in a name is invalid.

exception `zeroconf.EventLoopBlocked`

Bases: `zeroconf._exceptions.Error`

Exception when the event loop is blocked.

This exception is never expected to be thrown during normal operation. It should only happen when the cpu is maxed out or there is something blocking the event loop.

exception `zeroconf.IncomingDecodeError`

Bases: `zeroconf._exceptions.Error`

Exception when there is invalid data in an incoming packet.

exception `zeroconf.NamePartTooLongException`

Bases: `zeroconf._exceptions.Error`

Exception when the name is too long.

exception `zeroconf.NonUniqueNameException`

Bases: `zeroconf._exceptions.Error`

Exception when the name is already registered.

exception `zeroconf.NotRunningException`

Bases: `zeroconf._exceptions.Error`

Exception when an action is called with a zeroconf instance that is not running.

The instance may not be running because it was already shutdown or startup has failed in some unexpected way.

exception `zeroconf.ServiceNameAlreadyRegistered`

Bases: `zeroconf._exceptions.Error`

Exception when a service name is already registered.

Multicast DNS Service Discovery for Python, v0.14-wmcbirne Copyright 2003 Paul Scott-Murphy, 2014 William McBrine

This module provides a framework for the use of DNS Service Discovery using IP multicast.

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```
class zeroconf.asyncio.AsyncZeroconf (interfaces: Union[List[Union[str, int, Tuple[Tuple[str,
int, int], int]]], zeroconf._utils.net.InterfaceChoice]
    = <InterfaceChoice.All: 2>, unicast: bool = False,
    ip_version: Optional[zeroconf._utils.net.IPVersion]
    = None, apple_p2p: bool = False, zc: Op-
    tional[zeroconf._core.Zeroconf] = None)
```

Bases: `object`

Implementation of Zeroconf Multicast DNS Service Discovery

Supports registration, unregistration, queries and browsing.

The async version is currently a wrapper around Zeroconf which is now also async. It is expected that an asyncio event loop is already running before creating the AsyncZeroconf object.

async_add_service_listener (type_: str, listener: `zeroconf._services.ServiceListener`) → None

Adds a listener for a particular service type. This object will then have its `add_service` and `remove_service` methods called when services of that type become available and unavailable.

async_close () → None

Ends the background threads, and prevent this instance from servicing further queries.

async_get_service_info (type_: str, name: str, timeout: int = 3000, question_type: Optional[`zeroconf._dns.DNSQuestionType`] = None) → Optional[`zeroconf.asyncio.AsyncServiceInfo`]

Returns network's service information for a particular name and type, or None if no service matches by the timeout, which defaults to 3 seconds.

async_register_service (info: `zeroconf._services.info.ServiceInfo`, ttl: Optional[int] = None, allow_name_change: bool = False, cooperating_responders: bool = False) → Awaitable[T_co]

Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service. The name of the service may be changed if needed to make it unique on the network. Additionally multiple cooperating responders can register the same service on the network for resilience (if you want this behavior set `cooperating_responders` to `True`).

The service will be broadcast in a task. This task is returned and therefore can be awaited if necessary.

async_remove_all_service_listeners () → None

Removes a listener from the set that is currently listening.

async_remove_service_listener (listener: zeroconf._services.ServiceListener) → None

Removes a listener from the set that is currently listening.

async_unregister_all_services () → None

Unregister all registered services.

Unlike `async_register_service` and `async_unregister_service`, this method does not return a future and is always expected to be awaited since its only called at shutdown.

async_unregister_service (info: zeroconf._services.info.ServiceInfo) → Awaitable[T_co]

Unregister a service.

The service will be broadcast in a task. This task is returned and therefore can be awaited if necessary.

async_update_service (info: zeroconf._services.info.ServiceInfo) → Awaitable[T_co]

Registers service information to the network with a default TTL. Zeroconf will then respond to requests for information for that service.

The service will be broadcast in a task. This task is returned and therefore can be awaited if necessary.

```
class zeroconf.asyncio.AsyncServiceInfo (type_: str, name: str, port: Optional[int] = None,
                                         weight: int = 0, priority: int = 0, properties:
                                         Union[bytes, Dict[KT, VT]] = b'', server: Op-
                                         tional[str] = None, host_ttl: int = 120, other_ttl:
                                         int = 4500, *, addresses: Optional[List[bytes]]
                                         = None, parsed_addresses: Optional[List[str]] =
                                         None, interface_index: Optional[int] = None)
```

Bases: zeroconf._services.info.ServiceInfo

An async version of ServiceInfo.

```
class zeroconf.asyncio.AsyncServiceBrowser (zeroconf: zeroconf_core.Zeroconf,
                                             type_: Union[str, list], handlers:
                                             Union[zeroconf._services.ServiceListener,
                                             List[Callable[[...], None]],
                                             None] = None, listener: Op-
                                             tional[zeroconf._services.ServiceListener]
                                             = None, addr: Optional[str] = None, port:
                                             int = 5353, delay: int = 1000, question_type:
                                             Optional[zeroconf._dns.DNSQuestionType] =
                                             None)
```

Bases: zeroconf._services.browser._ServiceBrowserBase

Used to browse for a service for specific type(s).

Constructor parameters are as follows:

- *zc*: A Zeroconf instance
- *type_*: fully qualified service type name
- *handler*: ServiceListener or Callable that knows how to process ServiceStateChange events
- *listener*: ServiceListener
- *addr*: address to send queries (will default to multicast)
- *port*: port to send queries (will default to mdns 5353)

- *delay*: The initial delay between answering questions
- *question_type*: The type of questions to ask (DNSQuestionType.QM or DNSQuestionType.QU)

The listener object will have its `add_service()` and `remove_service()` methods called when this browser discovers changes in the services availability.

async_cancel () → None

Cancel the browser.

class `zeroconf.asyncio.AsyncZeroconfServiceTypes`

Bases: `zeroconf._services.types.ZeroconfServiceTypes`

An async version of `ZeroconfServiceTypes`.

classmethod `async_find` (*aiozc*: *Optional[AsyncZeroconf]* = None, *timeout*: *Union[int, float]* = 5, *interfaces*: *Union[List[Union[str, int, Tuple[Tuple[str, int, int], int]]], zeroconf._utils.net.InterfaceChoice]* = <InterfaceChoice.All: 2>, *ip_version*: *Optional[zeroconf._utils.net.IPVersion]* = None) → *Tuple[str, ...]*

Return all of the advertised services on any local networks.

Parameters

- **aiozc** – `AsyncZeroconf()` instance. Pass in if already have an instance running or if non-default interfaces are needed
- **timeout** – seconds to wait for any responses
- **interfaces** – interfaces to listen on.
- **ip_version** – IP protocol version to use.

Returns tuple of service type strings

See [the project's README](#) for more information.

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